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WorkBee Control Overview

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Step 1 — Header

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- WorkBee Control has only been
 tested on Google Chrome
 - The Name of the machine.
 - Advanced Users: The machine name can be changed by adding the command M550 "Machine Name" to config-user-settings.g
- Send Manual G-Code commands.
- To upload and start a job.
 - Make sure the machine has been Homed and Work Zero set.
- Triggers a software emergency stop.

Step 2 — Positions



- Current position in Work Coordinates.
 - The Work Coordinates displayed are determined by the Work Coordinate Selection dropdown.
 - Advanced Users: To find out the machine positions of all Work Coordinates open File Management > System > config-override.g
 - (i) Advanced Users: You can directly edit the machine positions of the Work Coordinates in config-override.g and save it.
- Current position in Machine Coordinates
 - (i) The machine <u>ALWAYS</u> moves within a Work Coordinate system. Machine coordinates are not a selectable coordinate system.
 - Advanced Users: To make absolute G-Code command movements in machine coordinates,
 G53 has to be explicitly stated at the beginning of each line.

Step 3 — Movement



- Used to home the machine. You need to home the machine when it is turned on.
 - When homing an individual axis, it will always home the Z first to insure it is clear of any work piece.
- Used to jog the machine around the work area. Right-click to modify distance.
 - The jogging feedrate can be modified under Settings > Machine Specific > 'Feedrate for move buttons (mm/min)'
- Used to set the Work Zero position for the selected Work Coordinate System.
- Move the machine to the Work Zero position of the currently selected Work Coordinate System.
- The Compensation and Calibration buttons allows a probe to measure the overall work area flatness.
 Height maps are useful for milling PCB's. More information on using these buttons can be found here: <u>https://duet3d.dozuki.com/Wiki/Using</u> <u>mes...</u>

Step 4 — Job Control



- When running a job, the progress of the job will be displayed here along with the percentage complete and estimated time remaining.
- When running a job, pause, resume, & cancel buttons will show here.
 When pausing a job it will save the current position and home the machine.
 - A controlled power off can also be performed in the middle of a job. This will pause, home and save the current job position, allowing it to be continued at a later time.
 - Use this button to resume a job after a controlled power off.
 - (i) This button can also be used to resume a job after an unexpected power loss.
- Advanced Users: 'Enable End G-Code' allows a set of pre-defined commands to be run after a job is completed.
 - These commands are defined under File Management > System
 > Sleep.g

Step 6 — Console

Step 5 — Job Control Continued



- When running a job these buttons allow micro-adjustment of the Z-Axis
 - For example if the job is not cutting deep enough, these buttons can be used to shift the job downwards.
- Be warned it will move the whole job downwards by same amount, including Z-Axis Safe Heights.
- A slider to speed up or slow down the job. The speed is represented by a percentage, with 100% being the normal speed.



Send Manual G-Code commands.

 Important information outputted from the WorkBee will be displayed here.

Step 7 — G-Code Viewer - Part 1



- Makes the G-Code Viewer Fullscreen.
- (i) Use the mouse scroll wheel to zoom in and out.
 - (i) Mouse Left-click to Orbit.
 - (i) Ctrl + Mouse Left-click to Pan.
- The grid shows the machines working area.
 - The X, Y, and Z-Axis markers show where the selected Work Zero is located in the machines working area.
- Current position in Work Coordinates.
- Software emergency stop.

Step 8 — G-Code Viewer - Part 2



- Loads the current Job.
- (i) In this mode it will only display progress thus far.
- Loads a local file from your computer.
- (i) If a job is running. Load the same job locally, and it will display the whole job, and you can view the cursors current position within that job.
 - (i) But it will not indicate progress.
- This will elongate the spaces between passes. It can make files much easier to view.

Step 9 — Jobs & Macros



- *i* This is where all the Jobs are stored.
 - Clicking on a Job will run the Job.
 - Right clicking on a Job will also allow the file to be run, and in addition: Simulate, Download, Edit, Rename, and Delete.
 - Create a sub-folder
 - Upload a job to the current folder
 - The Macros page is similar the Jobs page.
 - Macros are different to jobs in that they are a sequence of commands which are regularly run.
 - *i* For example a macro could be created that would move the head to the machine center instead of typing manual commands each time.

Step 10 — System



- This contains all the System files.
- Anything with 'config' in the name is run at startup.
 - We advise putting any custom settings in 'config-user-settings.g'
- *i* homeall.g, homex.g, homey.g, and homez.g contain the commands that are executed when the homing buttons are pressed.
- workzero.g contains the commands that are executed when 'Go To Work Zero' is pressed.



Step 11 — General Settings

- Change Theme Colour
- Autoclose Notifications
- Manage plugins packaged within WorkBee Control.
- Congifure Webcam. See <u>Duet's</u> <u>Dozuki.</u>

Step 12 — Machine Settings



- Change machine working area (No restart required)
- Change machine Steps/mm (No restart required)
- Sensor statuses
- Touch probe settings. See
 <u>Assembling Your Original WorkBee</u>
 <u>XYZ Touch Probe</u>

Thanks for following the guide. As mentioned this was just a brief outline of using WorkBee Control. Please visit our YouTube channel for more in-depth tutorials on operating a CNC Machine. Even though some of the videos on our YouTube channel use an older version of the WorkBee the concepts still apply!